

Markov Chain

Definition 44

The process $\{X_n\}$ is a *Markov chain* if it satisfies the Markov property:

$$\mathbb{P}(X_n = j | X_0 = x_0, \dots, X_{n-1} = i) = \mathbb{P}(X_n = j | X_{n-1} = i)$$

for all $i, j, x_0, \dots, x_{n-2} \in S$ and for all $n = 1, 2, 3, \dots$

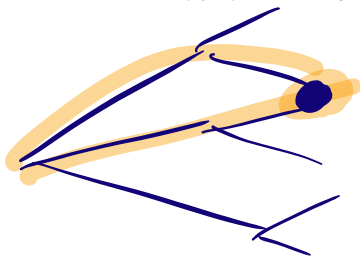
- The Markov property implies that:

$$\mathbb{P}(X_{n_k} = j | X_{n_0} = x_0, \dots, X_{n_{k-1}} = i) = \mathbb{P}(X_{n_k} = j | X_{n_{k-1}} = i)$$

for all k, n , all $n_0 \leq n_1 \leq \dots \leq n_{k-1} \leq n_k$ and all $i, j, x_0, \dots, x_{n_{k-1}}$

- Also

$$\mathbb{P}(X_{n+m} = j | X_0 = x_0, \dots, X_m = i) = \mathbb{P}(X_{n+m} = j | X_m = i)$$



Homogeneous Chain

- The evolution of a markov chain is defined by its transition probability, defined by $\mathbb{P}(X_{n+1} = j | X_n = i)$ (where without loss of generality we may assume that S is an integer set).

Definition 45

- The chain $\{X_n\}$ is called *homogeneous* if its transition probabilities do not depend on the time, i.e.,

$$\mathbb{P}(X_{n+1} = j | X_n = i) = \mathbb{P}(X_1 = j | X_0 = i)$$

for all n, i, j . The *transition probability matrix* $\mathbf{P} = [p_{i,j}]$ is the $|S| \times |S|$ matrix of the transition probabilities, such that $p_{i,j} = \mathbb{P}(X_{n+1} = j | X_n = i)$

Transition Matrix

Theorem

The transition matrix \mathbf{P} of a Markov chain is a *stochastic matrix*, that is, it has non-negative elements such that

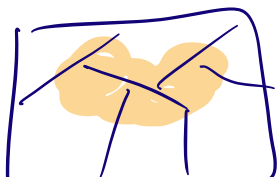
$$\sum_{j \in S} p_{i,j} = 1$$

(sum of the elements on each row yields 1)

- In order to characterize the probability for n steps transitions, we introduce the n -step transition probability matrix with elements

$$p_{i,j}(m, m+n) = \mathbb{P}(X_{m+n} = j | X_m = i)$$

- By homogeneity, we have that $\mathbf{P}(m, m+1) = \mathbf{P}$.
- Furthermore, $\mathbf{P}(m, m+n) \triangleq \mathbf{P}^{(n)}$ does not depend on m .



$$P(A) = P(A \cap B_1) + P(A \cap B_2) + \dots + P(A \cap B_n)$$
$$P(A|B_2) \cdot P(B_2)$$

Transition Matrix

Theorem

$$P(1, 3) = \sum_k P(1, 1+1) \cdot P(1+1, 1+2)$$

$$p_{i,j}(m, m+n+r) = \sum_k p_{i,k}(m, m+n) p_{k,j}(m+n, m+n+r)$$

Therefore, $P(m, m+n+r) = P(m, m+n)P(m+n, m+n+r)$. It follows that for homogeneous Markov chains, $P(m, m+n) = P^n$, i.e., $P^{(n)} = P^n$

P^2 - trans. matrix 2-step

P^3 - 3-steps ahead

$$P^3 = P \cdot P \cdot P$$

Initial State pmf

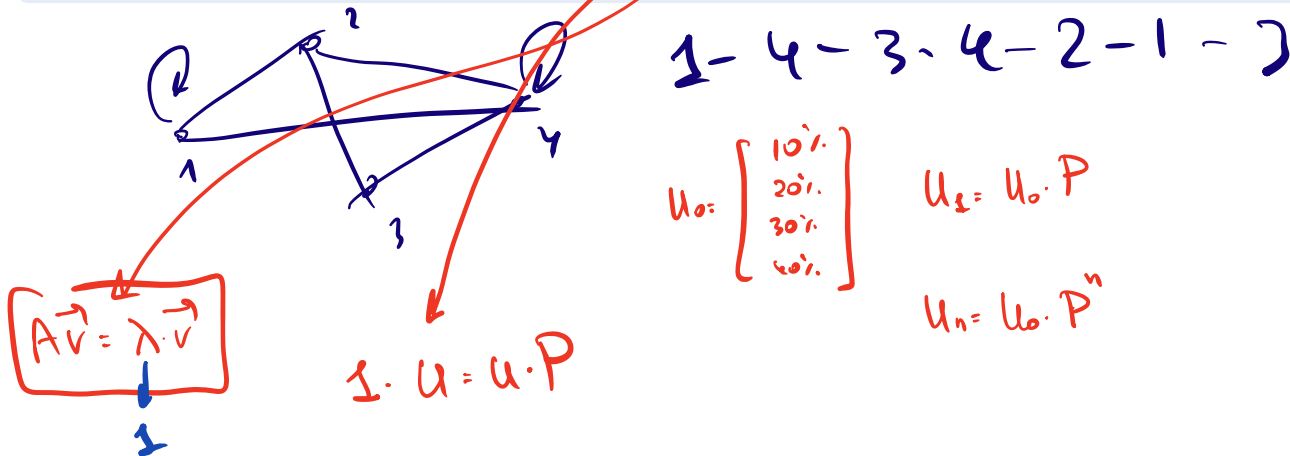
$$u_n = u_0 \cdot P^n$$

$$S = \{1, 2, 3, 4\}$$

- We let $\mathbf{u}(n)$ denote the pmf of X_n , that is, for each n we have that $\mathbf{u}(n)$ is a vector with $|S|$ non-negative components that sum to 1.

Lemma

$\mathbf{u}(m+n) = \mathbf{u}(m)\mathbf{P}^n$, and hence $\mathbf{u}(n) = \mathbf{u}(0)\mathbf{P}^n$. This describes the pmf of X_n in terms of the initial state pmf $\mathbf{u}(0)$.



Example

Let $S = \{1, 2, 3, 4, 5, 6\}$ and consider the transition matrix

$$\mathbf{P} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 & 0 & 0 & 0 \\ \frac{1}{4} & \frac{3}{4} & 0 & 0 & 0 & 0 \\ \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & 0 & 0 \\ \frac{1}{4} & 0 & \frac{1}{4} & \frac{1}{4} & 0 & \frac{1}{4} \\ 0 & 0 & 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 0 & 0 & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

Stationary Distribution

Definition

The vector π is called a *stationary distribution* of the chain if it has entries $\{\pi_j: j \in S\}$ such that:

a) $\pi_j \geq 0$ for all j , and $\sum_{j \in S} \pi_j = 1$.

b) it satisfies $\pi = \pi P$, that is, $\pi_j = \sum_i \pi_i p_{i,j}$ for all $j \in S$.

- This is called “stationary distribution” since if X_0 is distributed with $u(0) = \pi$, then all X_n will have the same distribution, in fact

$$u(n) = u(0)P^n = \pi P^n = \pi P P^{n-1} = \pi P^{n-1} = \dots = \pi$$

- Given the classification of chains and the decomposition theorem, we shall assume that the chain is *irreducible*, that is, its state space is formed by a single equivalence class of intercommunicating (persistent) states C or by the class of transient states T .

Stationary Distribution

Theorem

A irreducible chain has a stationary distribution π if and only if all states are *non-null persistent*. In this case, π is unique and satisfies $\pi_j = \frac{1}{\mu_j}$, where μ_j is the *mean recurrence time* of state j .

Let $S = \{1, 2\}$ and consider the transition matrix

$$\mathbf{P} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{4} & \frac{3}{4} \end{bmatrix}$$



Convergence

Convergence

Definition *Let $\{x_n, n \geq 1\}$ be a real-valued sequence, i.e., a map from \mathbb{N} to \mathbb{R} . We say that the sequence $\{x_n\}$ converges to some $x \in \mathbb{R}$ if there exists an $n_0 \in \mathbb{N}$ such that for all $\epsilon > 0$,*

$$|x_n - x| < \epsilon, \forall n \geq n_0.$$

We say that the sequence $\{x_n\}$ converges to $+\infty$ if for any $M > 0$, there exists an $n_0 \in \mathbb{N}$ such that for all $n \geq n_0$, $x_n > M$.

We say that the sequence $\{x_n\}$ converges to $-\infty$ if for any $M > 0$, there exists an $n_0 \in \mathbb{N}$ such that for all $n \geq n_0$, $x_n < -M$.

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space and let $\{X_n\}_{n \in \mathbb{N}}$ be a sequence of real-valued random variables defined on this probability space.

Convergence

Definition [Definition 0 (Point-wise convergence or sure convergence)]

A sequence of random variables $\{X_n\}_{n \in \mathbb{N}}$ is said to converge point-wise or surely to X if

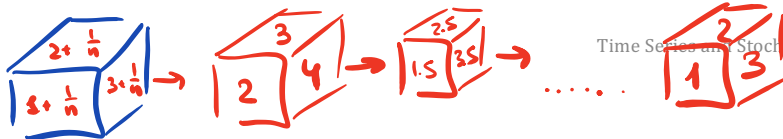
$$X_n(\omega) \rightarrow \underline{\underline{X(\omega)}}, \quad \forall \omega \in \Omega.$$

$\omega =$
0
1

$X_n(0) : X_1, X_2, X_3$



$X_n(1) : X_4, X_5, X_6$

Time Series and Stochastic Processes

Convergence

Definition

Definition 1 (Almost sure convergence or convergence with probability 1)

A sequence of random variables $\{X_n\}_{n \in \mathbb{N}}$ is said to converge almost surely or with probability 1 (denoted by a.s. or w.p. 1) to X if

$$\mathbb{P}(\underbrace{\{\omega | X_n(\omega) \rightarrow X(\omega)\}}) = 1.$$

Convergence

Definition [Definition 2 (convergence in probability)]

A sequence of random variables $\{X_n\}_{n \in \mathbb{N}}$ is said to converge in probability (denoted by i.p.) to X if

$$\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| > \epsilon) = 0, \quad \forall \epsilon > 0.$$

Convergence

Definition [Definition 3 (convergence in r^{th} mean)]

A sequence of random variables $\{X_n\}_{n \in \mathbb{N}}$ is said to converge in r^{th} mean to X if

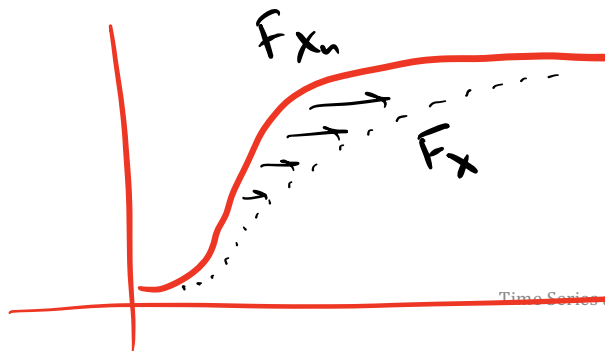
$$\lim_{n \rightarrow \infty} \mathbb{E}[|X_n - X|^r] = 0.$$

Convergence

Definition [Definition 4 (convergence in distribution or weak convergence)]

A sequence of random variables $\{X_n\}_{n \in \mathbb{N}}$ is said to converge in distribution to X if

$$\lim_{n \rightarrow \infty} F_{X_n}(x) = F_X(x), \quad \forall x \in \mathbb{R} \text{ where } F_X(\cdot) \text{ is continuous.}$$



Convergence

- (1) *Point-wise Convergence*: $X_n \xrightarrow{\text{p.w.}} X$.
- (2) *Almost sure Convergence*: $X_n \xrightarrow{\text{a.s.}} X$ or $X_n \xrightarrow{\text{w.p.}^1} X$.
- (3) *Convergence in probability*: $X_n \xrightarrow{\text{i.p.}} X$.
- (4) *Convergence in r^{th} mean*: $X_n \xrightarrow{r} X$. When $r = 2$, $X_n \xrightarrow{\text{m.s.}} X$.
- (5) *Convergence in Distribution*: $X_n \xrightarrow{\text{D}} X$.

Convergence

Example: Consider the probability space $(\Omega, \mathcal{F}, \mathbb{P}) = ([0, 1], \mathcal{B}([0, 1]), \lambda)$ and a sequence of random variables $\{X_n, n \geq 1\}$ defined by

$$X_n(\omega) = \begin{cases} n, & \text{if } \omega \in [0, \frac{1}{n}] , \\ 0, & \text{otherwise.} \end{cases}$$

Convergence

$$X_n = \begin{cases} n, & \text{with probability } \frac{1}{n}, \\ 0, & \text{with probability } 1 - \frac{1}{n}. \end{cases}$$

Clearly, when $\omega \neq 0$, $\lim_{n \rightarrow \infty} X_n(\omega) = 0$ but it diverges for $\omega = 0$. This suggests that the limiting random variable must be the constant random variable 0. Hence, except at $\omega = 0$, the sequence of random variables converges to the constant random variable 0. Therefore, this sequence does not converge surely, but converges almost surely.

Convergence

For some $\epsilon > 0$, consider

$$\begin{aligned}\lim_{n \rightarrow \infty} \mathbb{P}(|X_n| > \epsilon) &= \lim_{n \rightarrow \infty} \mathbb{P}(X_n = n), \\ &= \lim_{n \rightarrow \infty} \left(\frac{1}{n}\right), \\ &= 0.\end{aligned}$$

Hence, the sequence converges in probability.

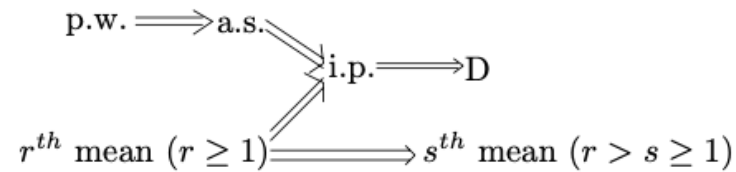
Convergence

Consider the following two expressions:

$$\begin{aligned}\lim_{n \rightarrow \infty} \mathbb{E}[|X_n|^2] &= \lim_{n \rightarrow \infty} \left(n^2 \times \frac{1}{n} + 0 \right), \\ &= \infty.\end{aligned}$$

$$\begin{aligned}\lim_{n \rightarrow \infty} \mathbb{E}[|X_n|] &= \lim_{n \rightarrow \infty} \left(n \times \frac{1}{n} + 0 \right), \\ &= 1.\end{aligned}$$

Convergence



Convergence

Theorem $X_n \xrightarrow{r} X \implies X_n \xrightarrow{i.p.} X, \quad \forall r \geq 1.$

Proof: Consider the quantity $\lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| > \epsilon)$. Applying Markov's inequality, we get

$$\begin{aligned} \lim_{n \rightarrow \infty} \mathbb{P}(|X_n - X| > \epsilon) &\leq \lim_{n \rightarrow \infty} \frac{\mathbb{E}[|X_n - X|^r]}{\epsilon^r}, \quad \forall \epsilon > 0, \\ &\stackrel{(a)}{=} 0, \end{aligned}$$

where (a) follows since $X_n \xrightarrow{r} X$. Hence proved.

$$P(|A| > \epsilon) \leq \frac{E(A^r)}{\epsilon^r}$$

Convergence

Theorem $X_n \xrightarrow{\text{i.p.}} X \implies \underline{X_n \xrightarrow{D} X}.$

Proof: Fix an $\epsilon > 0$.

$$\begin{aligned} F_{X_n}(x) &= \mathbb{P}(X_n \leq x), \\ &= \mathbb{P}(X_n \leq x, X \leq x + \epsilon) + \mathbb{P}(X_n \leq x, X > x + \epsilon), \\ &\leq F_X(x + \epsilon) + \mathbb{P}(|X_n - X| > \epsilon). \end{aligned}$$

Similarly,

$$\begin{aligned} F_X(x - \epsilon) &= \mathbb{P}(X \leq x - \epsilon), \\ &= \mathbb{P}(X \leq x - \epsilon, X_n \leq x) + \mathbb{P}(X \leq x - \epsilon, X_n > x), \\ &\leq F_{X_n}(x) + \mathbb{P}(|X_n - X| > \epsilon). \end{aligned}$$

Thus,

$$F_X(x - \epsilon) - \mathbb{P}(|X_n - X| > \epsilon) \leq F_{X_n}(x) \leq F_X(x + \epsilon) + \mathbb{P}(|X_n - X| > \epsilon).$$

As $n \rightarrow \infty$, since $X_n \xrightarrow{\text{i.p.}} X$, $\mathbb{P}(|X_n - X| > \epsilon) \rightarrow 0$. Therefore,

$$F_X(x - \epsilon) \leq \liminf_{n \rightarrow \infty} F_{X_n}(x) \leq \limsup_{n \rightarrow \infty} F_{X_n}(x) \leq F_X(x + \epsilon), \quad \forall \epsilon > 0.$$

If F is continuous at x , then $F_X(x - \epsilon) \uparrow F_X(x)$ and $F_X(x + \epsilon) \downarrow F_X(x)$ as $\epsilon \downarrow 0$. Hence proved.

Convergence

✓ $E((X_n - X)^r) \rightarrow 0$ $E((X_n - X)^s) \rightarrow 0$?

Theorem $X_n \xrightarrow{r} X \implies X_n \xrightarrow{s} X$, if $r > s \geq 1$.

$$(\mathbb{E}[|X_n - X|^s])^{1/s} \leq (\mathbb{E}[|X_n - X|^r])^{1/r},$$

$$(E(A^s))^{1/s} \leq (E(A^r))^{1/r} \quad s < r$$

Convergence

Theorem $X_n \xrightarrow{\text{i.p.}} X \not\Rightarrow X_n \xrightarrow{\text{r}} X$ in general.

Proof: Proof by counter-example:

Let X_n be an independent sequence of random variables defined as

$$X_n = \begin{cases} n^3, & \text{w.p. } \frac{1}{n^2}, \\ 0, & \text{w.p. } 1 - \frac{1}{n^2}. \end{cases}$$

Then, $\mathbb{P}(|X_n| > \epsilon) = \frac{1}{n^2}$ for large enough n , and hence $X_n \xrightarrow{\text{i.p.}} 0$. On the other hand, $\mathbb{E}[|X_n|] = n$, which diverges to infinity as n grows unbounded. ■

Convergence

Theorem $X_n \xrightarrow{D} X \not\Rightarrow X_n \xrightarrow{i.p.} X$ in general.

Proof: Proof by counter-example:

Let X be a Bernoulli random variable with parameter 0.5, and define a sequence such that $X_i = X \forall i$. Let $Y = 1 - X$. Clearly, $X_i \xrightarrow{D} Y$. But, $|X_i - Y| = 1, \forall i$. Hence, X_i does not converge to Y in probability. ■

Convergence

Theorem $X_n \xrightarrow{\text{i.p.}} X \not\Rightarrow X_n \xrightarrow{\text{a.s.}} X$ in general.

Proof: Proof by counter-example:

Let $\{X_n\}$ be a sequence of independent random variables defined as

$$X_n = \begin{cases} 1, & \text{w.p. } \frac{1}{n}, \\ 0, & \text{w.p. } 1 - \frac{1}{n}. \end{cases}$$

$$\rightarrow X_n = \begin{cases} 1, & \frac{1}{2} \\ 0, & \frac{1}{2} \end{cases}$$

$\lim_{n \rightarrow \infty} \mathbb{P}(|X_n| > \epsilon) = \lim_{n \rightarrow \infty} \mathbb{P}(X_n = 1) = \lim_{n \rightarrow \infty} \frac{1}{n} = 0$. So, $X_n \xrightarrow{\text{i.p.}} 0$.

Let A_n be the event that $\{X_n = 1\}$. Then, A_n 's are independent and $\sum_{n=1}^{\infty} \mathbb{P}(A_n) = \infty$. By Borel-Cantelli Lemma 2, w.p. 1 infinitely many A_n 's will occur, i.e., $\{X_n = 1\}$ i.o.. So, X_n does not converge to 0 almost surely. ■

Moment generating Function

Convergence

Theorem $X_n \xrightarrow{s} X \not\Rightarrow X_n \xrightarrow{r} X$ if $r > s \geq 1$ in general.

Proof: Proof by counter-example:

Let $\{X_n\}$ be a sequence of independent random variables defined as

$$X_n = \begin{cases} n, & \text{w.p. } \frac{1}{n^{\frac{r+s}{2}}}, \\ 0, & \text{w.p. } 1 - \frac{1}{n^{\frac{r+s}{2}}}. \end{cases}$$

Hence, $\mathbb{E}[|X_n^s|] = n^{\frac{s-r}{2}} \rightarrow 0$. But, $\mathbb{E}[|X_n^r|] = n^{\frac{r-s}{2}} \rightarrow \infty$.

Convergence

Theorem $X_n \xrightarrow{\text{m.s.}} X \not\Rightarrow X_n \xrightarrow{\text{a.s.}} X$ in general.

Proof: Proof by counter-example:

Let $\{X_n\}$ be a sequence of independent random variables defined as

$$X_n = \begin{cases} 1, & \text{w.p. } \frac{1}{n}, \\ 0, & \text{w.p. } 1 - \frac{1}{n}. \end{cases}$$

$\mathbb{E}[X_n^2] = \frac{1}{n}$. So, $X_n \xrightarrow{\text{m.s.}} 0$. X_n does not converge to 0 almost surely.

Convergence

Theorem $X_n \xrightarrow{\text{a.s.}} X \not\Rightarrow X_n \xrightarrow{\text{m.s.}} X$ in general.

Proof: Proof by counter-example:

Let $\{X_n\}$ be a sequence of independent of random variables defined as

$$X_n(\omega) = \begin{cases} n, & \omega \in (0, \frac{1}{n}), \\ 0, & \text{otherwise.} \end{cases}$$

We know that X_n converges to 0 almost surely. $\mathbb{E}[X_n^2] = n \rightarrow \infty$. So, X_n does not converge to 0 in the mean-squared sense. ■

Before proving the implication $X_n \xrightarrow{\text{a.s.}} X \Rightarrow X_n \xrightarrow{\text{i.p.}} X$, we derive a sufficient condition followed by a necessary and sufficient condition for almost sure convergence.

Convergence

Theorem 28.20 [Skorokhod's Representation Theorem]

Let $\{X_n, n \geq 1\}$ and X be random variables on $(\Omega, \mathcal{F}, \mathbb{P})$ such that X_n converges to X in distribution. Then, there exists a probability space $(\Omega', \mathcal{F}', \mathbb{P}')$, and random variables $\{Y_n, n \geq 1\}$ and Y on $(\Omega', \mathcal{F}', \mathbb{P}')$ such that,

- a) $\{Y_n, n \geq 1\}$ and Y have the same distributions as $\{X_n, n \geq 1\}$ and X respectively.*
- b) $Y_n \xrightarrow{a.s.} Y$ as $n \rightarrow \infty$.*

Convergence

Theorem 28.21 [Continuous Mapping Theorem]

If $X_n \xrightarrow{D} X$, and $g : \mathbb{R} \rightarrow \mathbb{R}$ is continuous, then $g(X_n) \xrightarrow{D} g(X)$.

Proof: By Skorokhod's Representation Theorem, there exists a probability space $(\Omega', \mathcal{F}', \mathbb{P}')$, and $\{Y_n, n \geq 1\}$, Y on $(\Omega', \mathcal{F}', \mathbb{P}')$ such that, $Y_n \xrightarrow{a.s.} Y$. Further, from continuity of g ,

$$\{\omega \in \Omega' \mid g(Y_n(\omega)) \rightarrow g(Y(\omega))\} \supseteq \{\omega \in \Omega' \mid Y_n(\omega) \rightarrow Y(\omega)\},$$

$$\Rightarrow \mathbb{P}(\{\omega \in \Omega' \mid g(Y_n(\omega)) \rightarrow g(Y(\omega))\}) \geq \mathbb{P}(\{\omega \in \Omega' \mid Y_n(\omega) \rightarrow Y(\omega)\}),$$

$$\Rightarrow \mathbb{P}(\{\omega \in \Omega' \mid g(Y_n(\omega)) \rightarrow g(Y(\omega))\}) \geq 1,$$

$$\Rightarrow g(Y_n) \xrightarrow{a.s.} g(Y),$$

$$\Rightarrow g(Y_n) \xrightarrow{D} g(Y).$$

This completes the proof since, $g(Y_n)$ has the same distribution as $g(X_n)$, and $g(Y)$ has the same distribution as $g(X)$. ■

Convergence

Theorem 28.23 If $X_n \xrightarrow{D} X$, then $C_{X_n}(t) \rightarrow C_X(t)$, $\forall t$.

Proof: If $X_n \xrightarrow{D} X$, from Skorokhod's Representation Theorem, there exist random variables $\{Y_n\}$ and Y such that $Y_n \xrightarrow{a.s.} Y$.

So,

$$\cos(Y_n t) \rightarrow \cos(Y t), \quad \cos(X_n t) \rightarrow \cos(X t), \quad \forall t.$$

As $\cos(\cdot)$ and $\sin(\cdot)$ are bounded functions,

$$\mathbb{E}[\cos(Y_n t)] + i\mathbb{E}[\sin(Y_n t)] \rightarrow \mathbb{E}[\cos(Y t)] + i\mathbb{E}[\sin(Y t)], \quad \forall t.$$

$$\Rightarrow C_{Y_n}(t) \rightarrow C_Y(t), \quad \forall t.$$

We get,

$$C_{X_n}(t) \rightarrow C_X(t), \quad \forall t,$$

since distributions of $\{X_n\}$ and X are same as those of $\{Y_n\}$ and Y respectively, from Skorokhod's Representation Theorem. ■

Convergence

Example 1: Let the random variable U be uniformly distributed on $[0, 1]$. Consider the sequence defined as:

$$X(n) = \frac{(-1)^n U}{n}.$$

1. *Almost sure convergence:* Suppose

$$U = a.$$

The sequence becomes

$$X_1 = -a,$$

$$X_2 = \frac{a}{2},$$

$$X_3 = -\frac{a}{3},$$

$$X_4 = \frac{a}{4},$$

$$\vdots$$

In fact, for any $a \in [0, 1]$

$$\lim_{n \rightarrow \infty} X_n = 0,$$

therefore, $X_n \xrightarrow{a.s.} 0$.

Convergence

Convergence in mean square sense:

In order to answer this question, we need to prove that

$$\lim_{n \rightarrow \infty} E[|X_n - 0|^2] = 0.$$

We know that,

$$\begin{aligned}\lim_{n \rightarrow \infty} E[|X_n - 0|^2] &= \lim_{n \rightarrow \infty} E[X_n^2], \\ &= \lim_{n \rightarrow \infty} E\left[\frac{U^2}{n^2}\right], \\ &= \lim_{n \rightarrow \infty} \frac{1}{n^2} E[U^2], \\ &= \lim_{n \rightarrow \infty} \frac{1}{n^2} \int_0^1 u^2 du, \\ &= \lim_{n \rightarrow \infty} \frac{1}{n^2} \left[\frac{u^3}{3}\right]_0^1, \\ &= \lim_{n \rightarrow \infty} \frac{1}{3n^2}, \\ &= 0.\end{aligned}$$

Hence, $X_n \xrightarrow{m.s.} 0$.